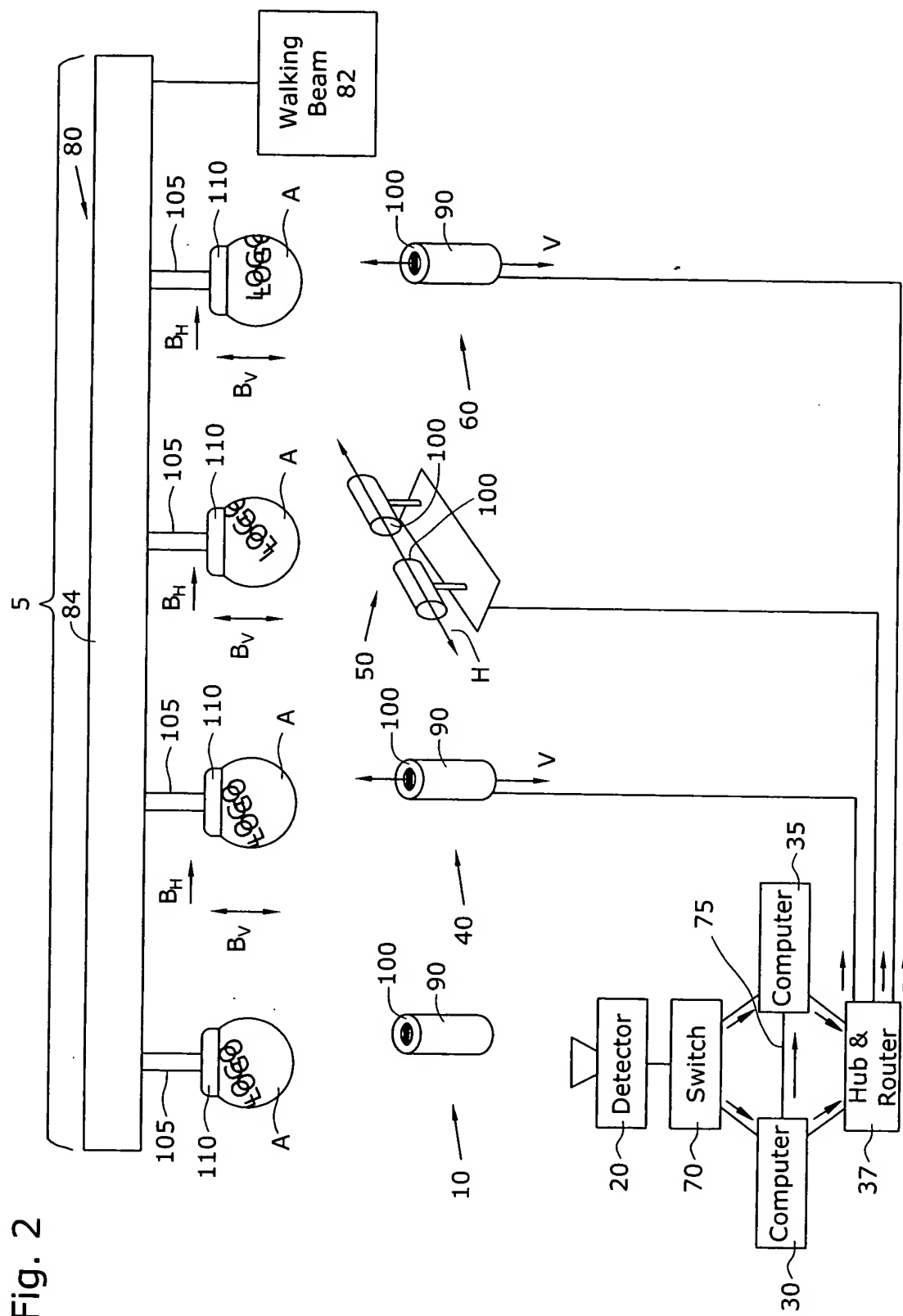


Fig. 1

[illegible]

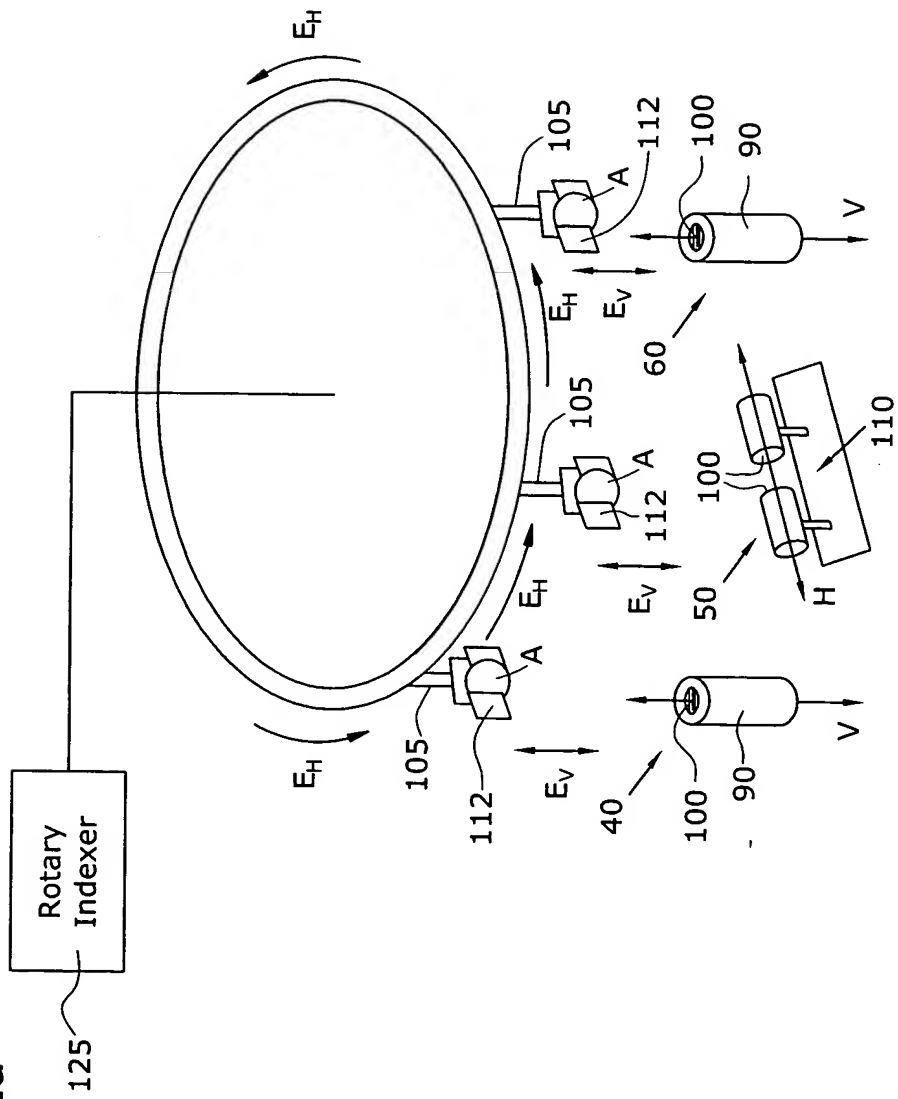
[illegible]

Fig. 3

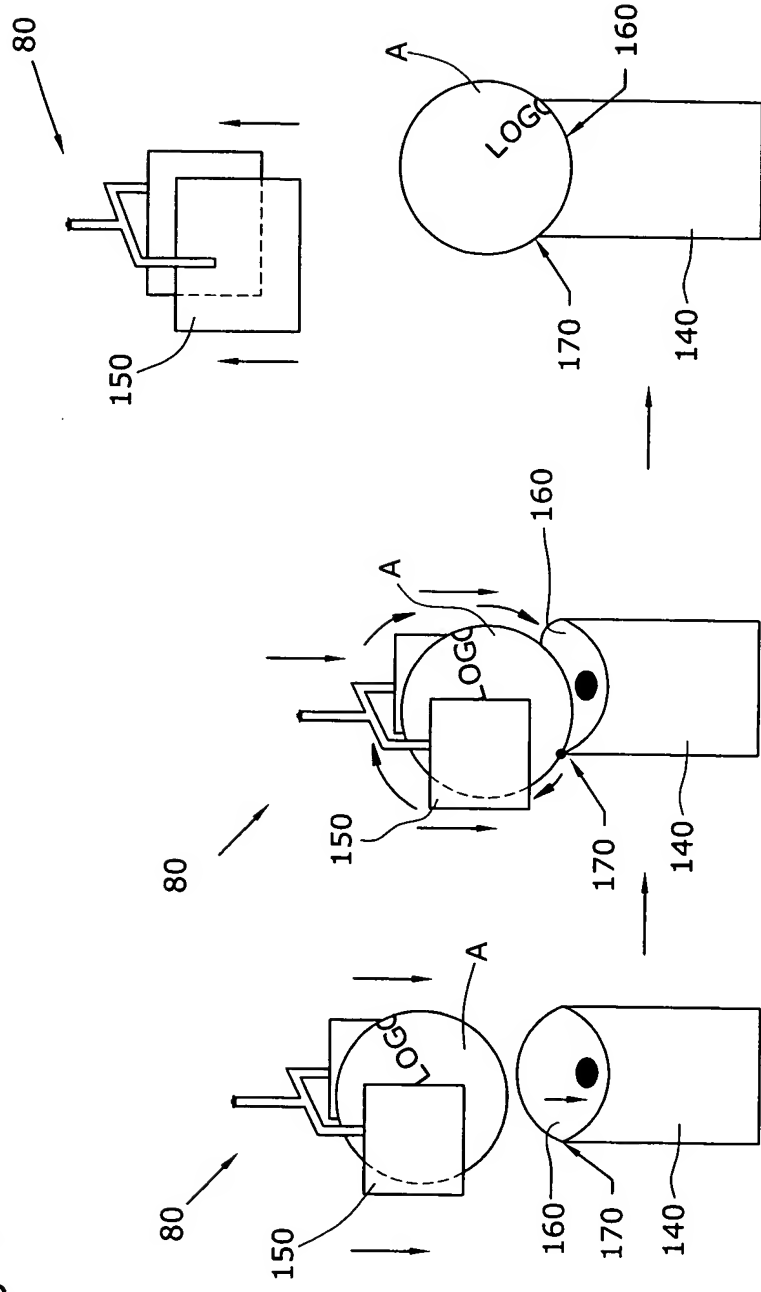


Fig. 4

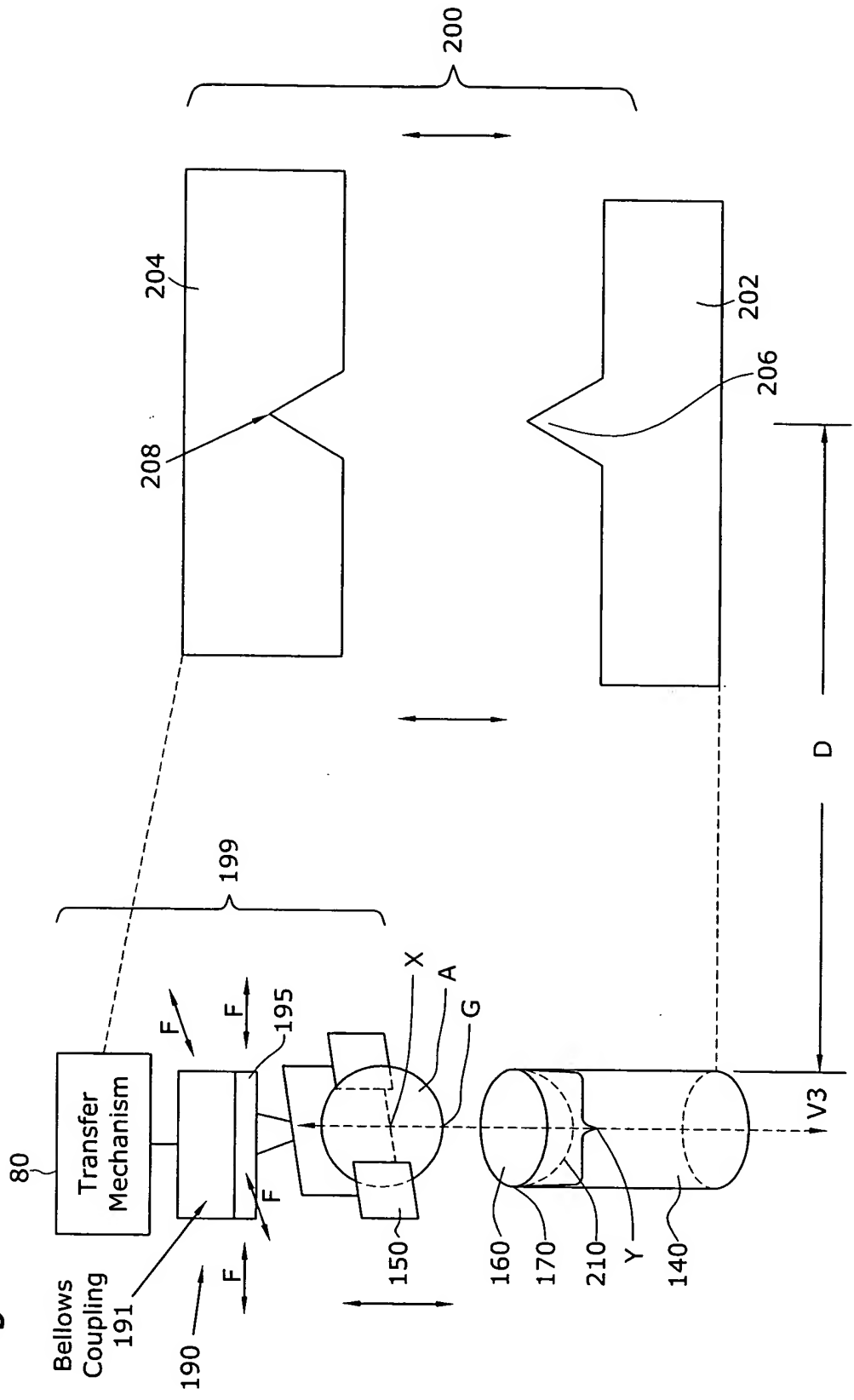
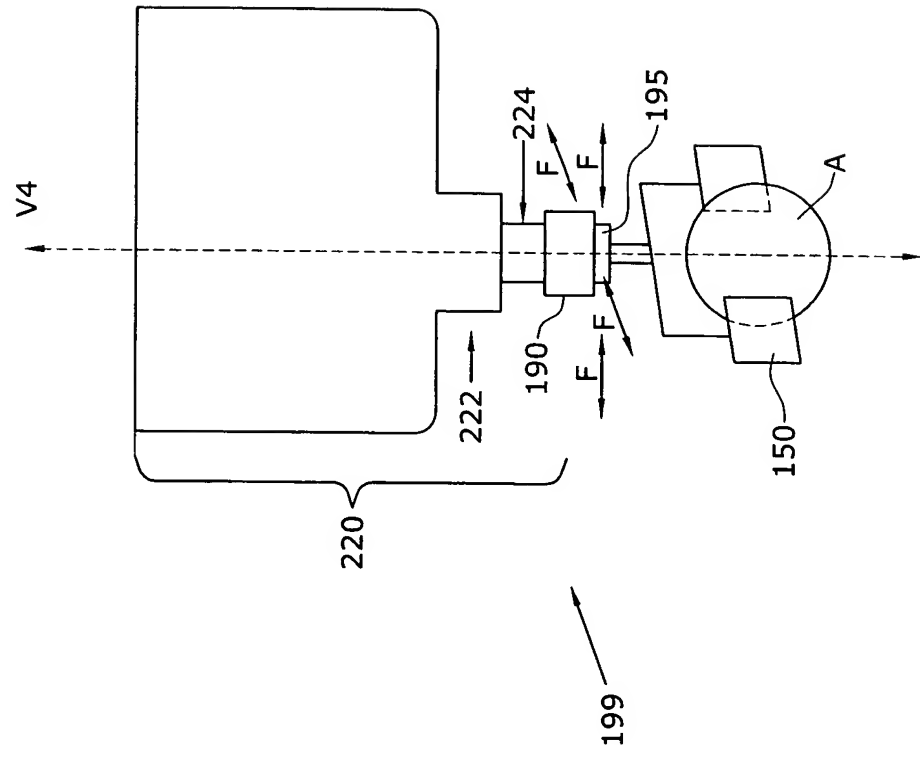


Fig. 5



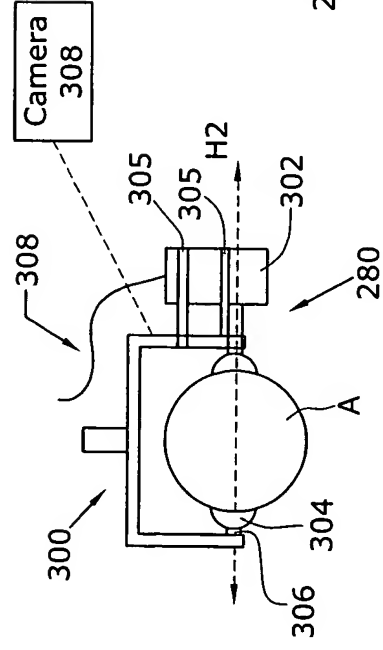


Fig. 6a

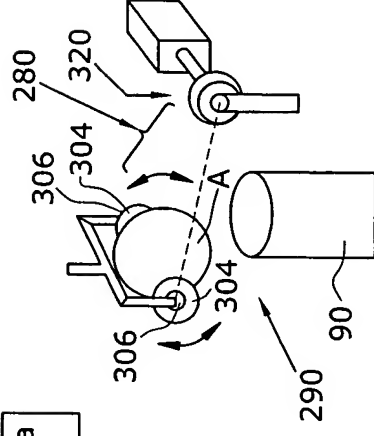


Fig. 6b

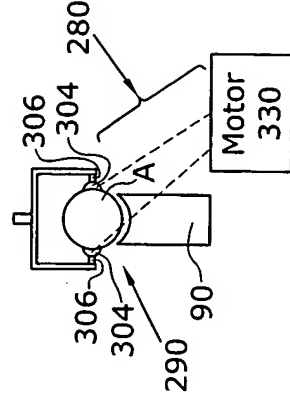


Fig. 6c

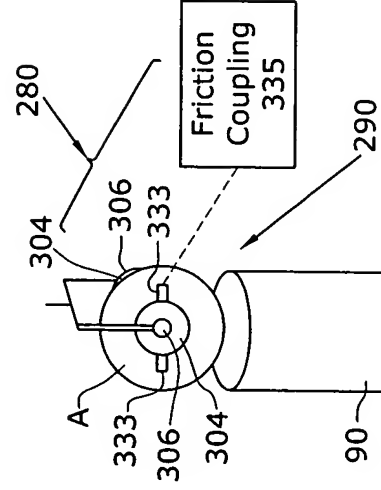


Fig. 6d

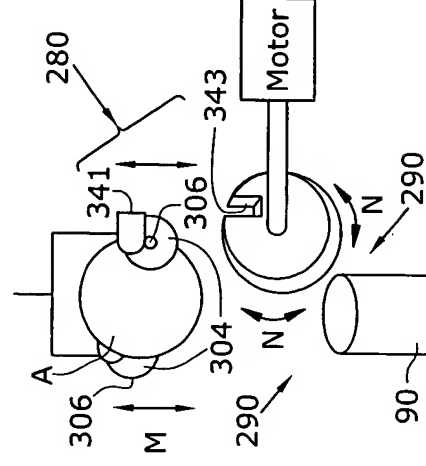


Fig. 6e

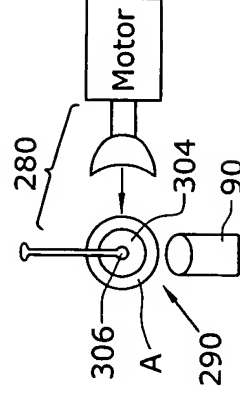


Fig. 6f

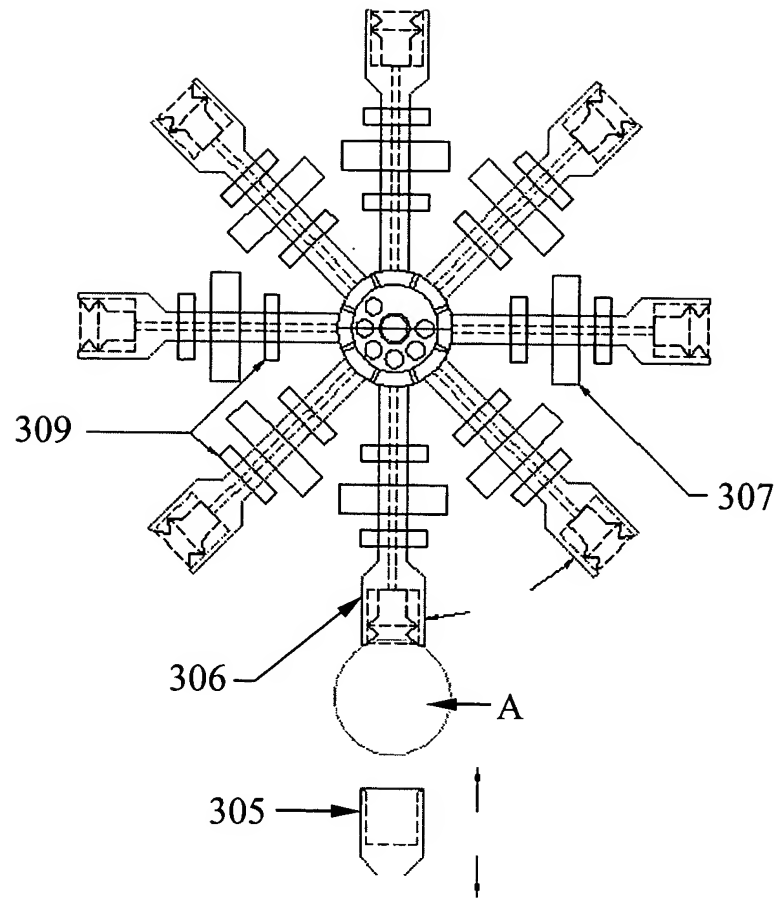
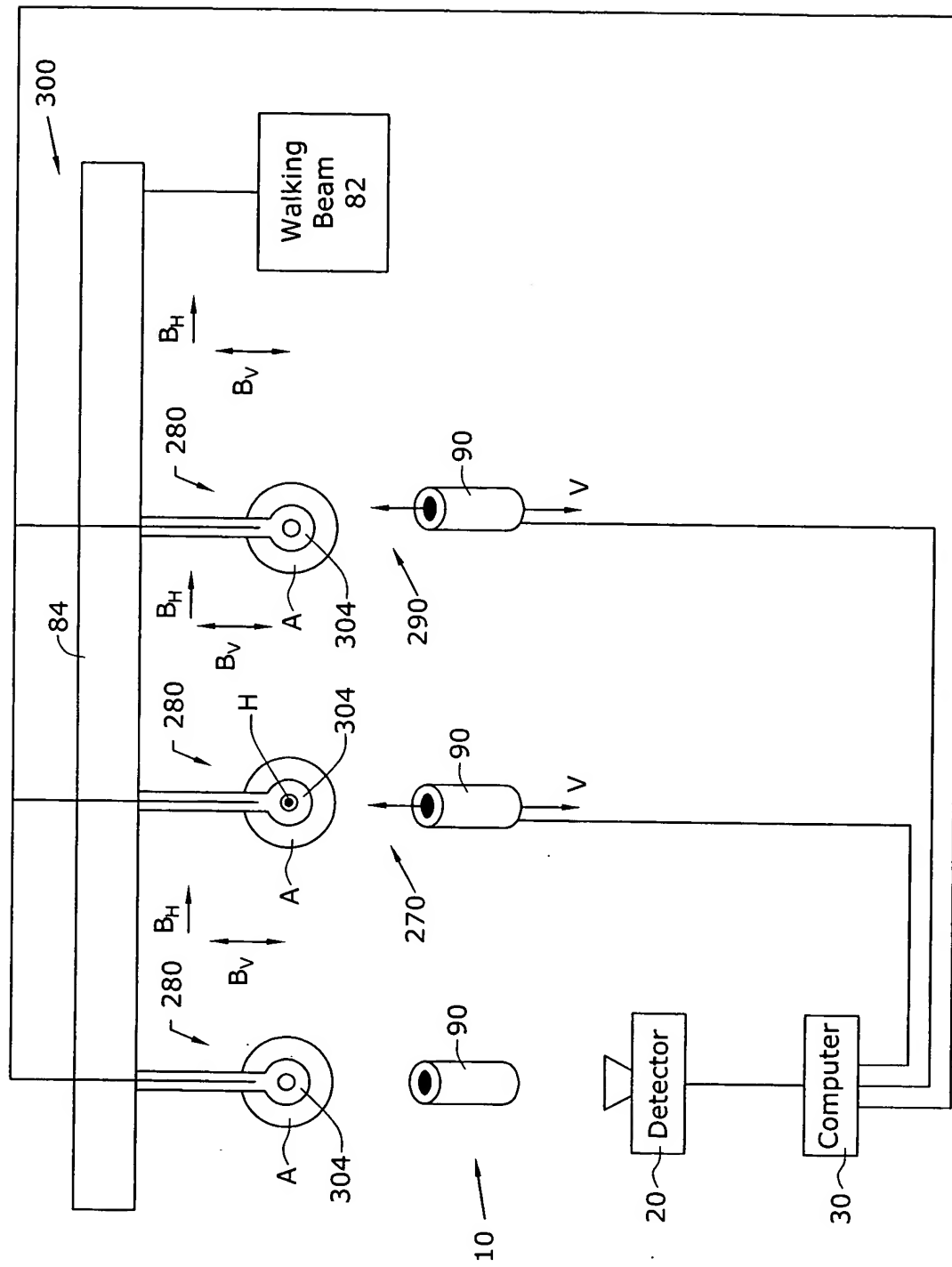


FIG. 6g

The schematic diagram illustrates a laser interferometer setup. A horizontal base plate 300 supports three vertical assemblies. Each assembly includes a circular component 304 with a central point labeled A. The middle assembly also features a label H. These components are connected via rods 280 to a horizontal bar 84. Horizontal movement vectors B_H and vertical movement vectors B_V are indicated for each assembly. A 'Walking Beam' 82 is positioned above the bar 84. Three cylindrical detectors 90 are aligned vertically below the points A; the middle one is specifically labeled 270. A signal path leads from the detectors through a 'Detector' unit 20 to a 'Computer' unit 30.



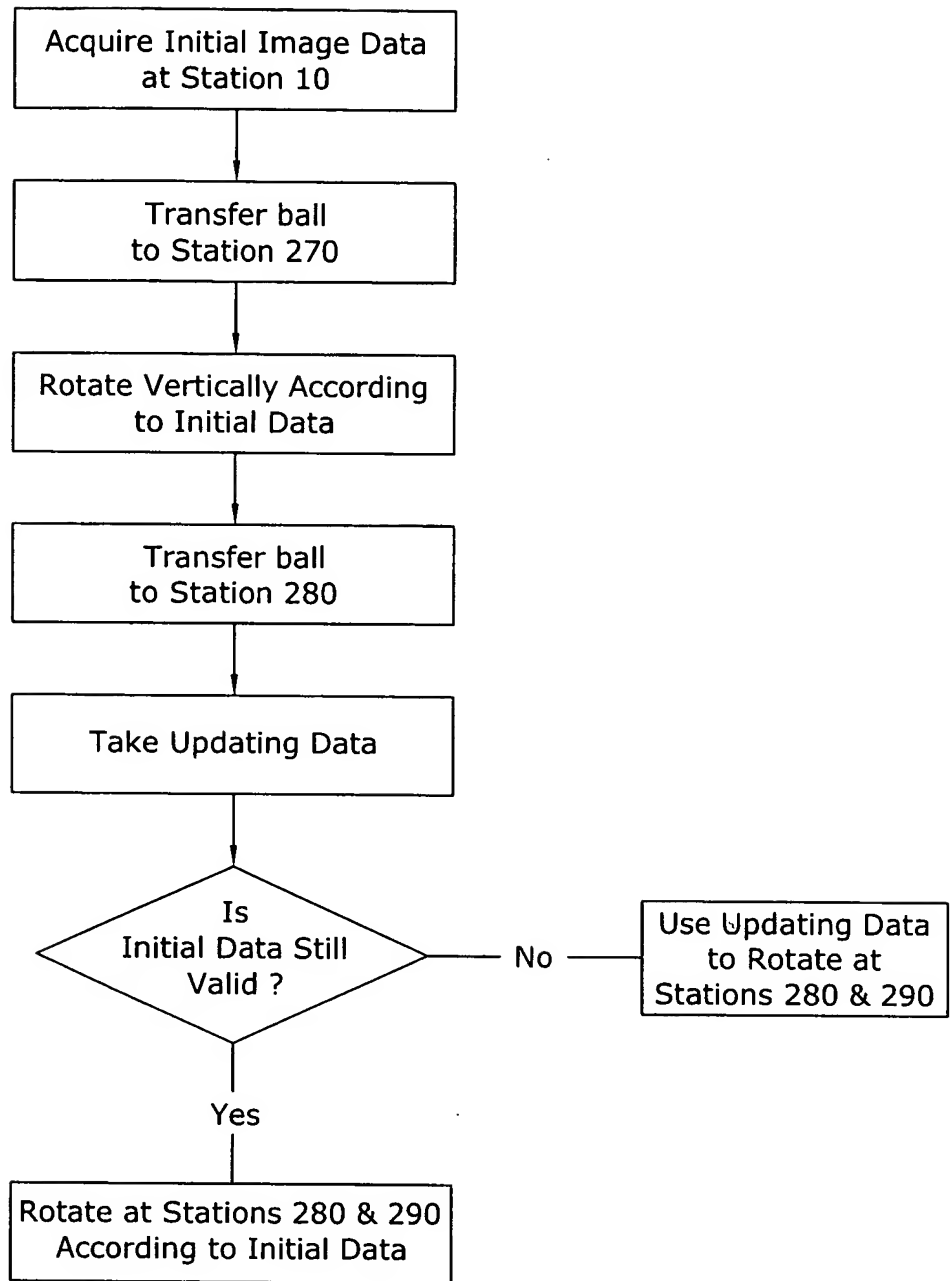


FIG. 7

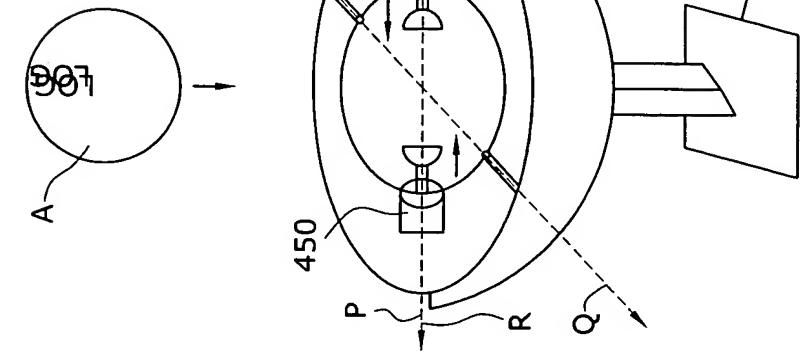


Fig. 8a

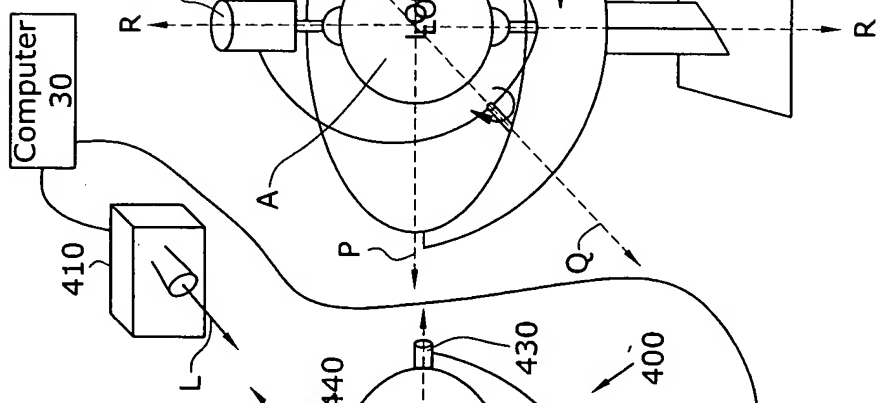


Fig. 8b

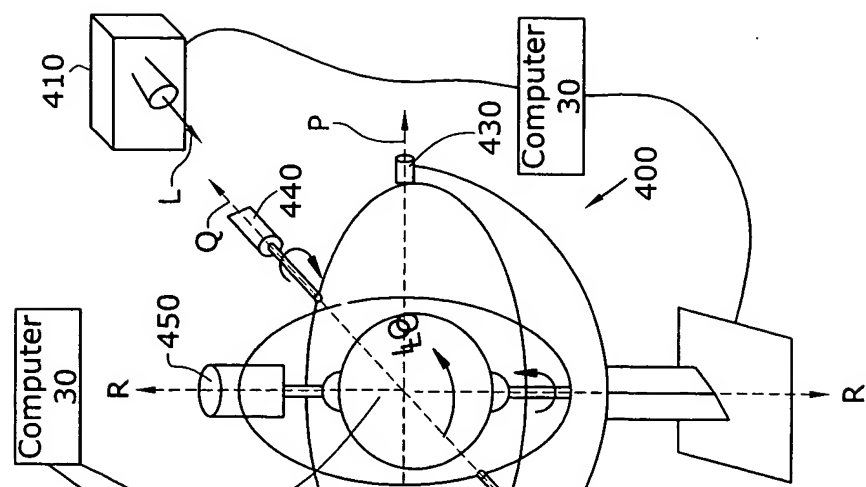


Fig. 8c

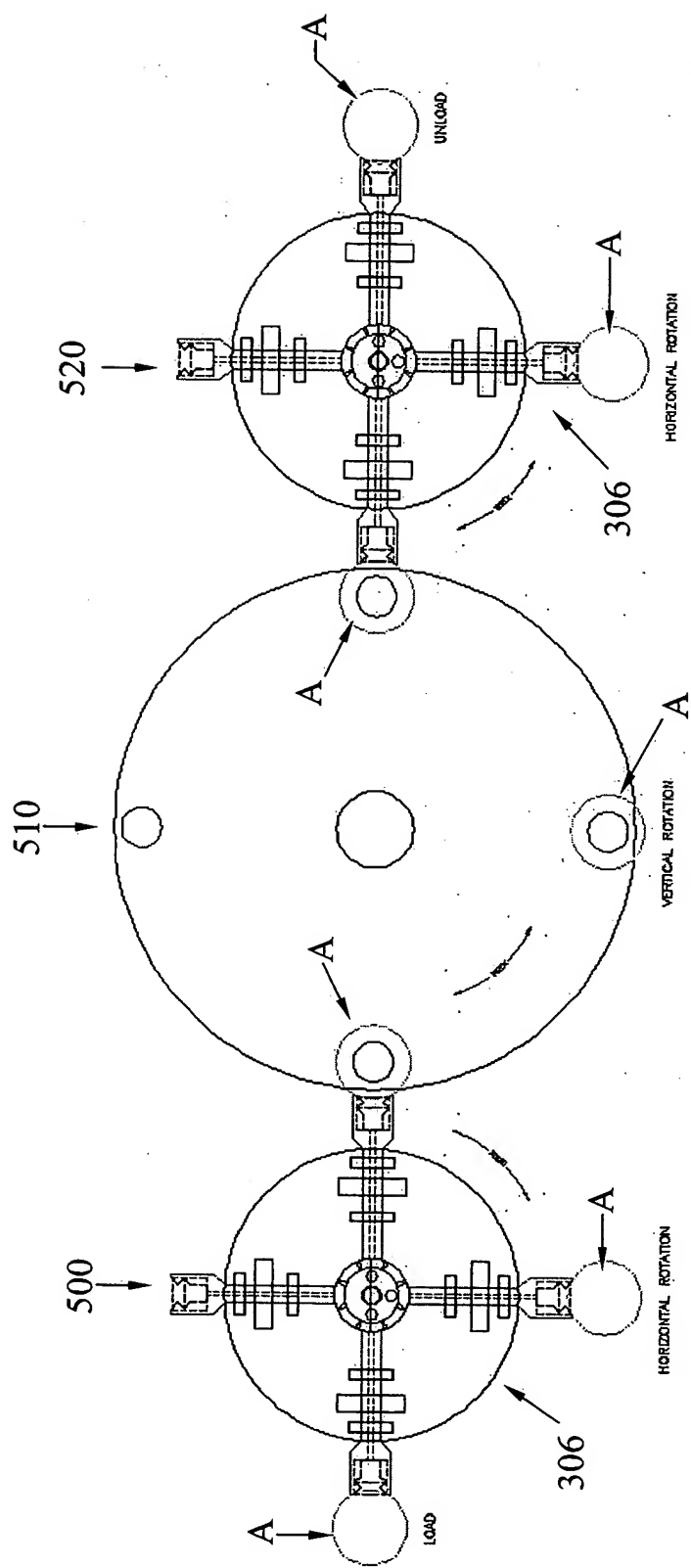


FIG. 9